PDOManager User Manual

PDOManager is a parameters configuration software for CAN bus.

🔀 PDOManager 📃
Receive PDO-Mapping Send PDO-Mapping NODE ID: Image: Download Image: Download Image: Download Image: Download <

This software include two parts: PDO Setting and Upload/Download.

Fieldbus Configuration in Kinco HMIware Software

	100 H UN I Network Device Setting
Field Bus Setting	x
Device (HMI (PLC	
Device Name: HMIO	 Protocol CANOpen Node Slave
Parameters Setting	
1 Predefined PDO Mapping Parameters	2: Enter Operational State Automatically
n.	yes •
3: Baud rate	4: Extended frame
125K	• no •
5: TXPDO Send Initial Value	6: Node ID
yes	• 2
Reset Default Parameters	OK Cancel

The parameter "Predefined PDO Mapping Parameters" must be set as "no". "Node ID" must be set according to the actual situation. The range is 1~127.

PDO Setting

PDO Setting is used to edit PDO file.

Before editing PDO file, firstly it need to press Load EDS file to add a EDS

file, which is the basic of editing PDO file.

After open a EDS file, then it can start to edit PDO. There are 4 operations for editing PDO as follows.

- (1) Add a new object.
- (2) Edit the attribute of PDO, press

Properties ,it will popup following dialog box:

PDO properties		×
COB-ID: Inhibit Time(100us): Transmission Type: Number of Syncs: Event time:	\$NodeID+0x300 0 asyschronous - device ▼ 0	Cancel

Then edit the attribute of PDO in this dialog box.

(3) Insert PDO insert PDO

When there is PDO for adding, press this button.

(4) Delete PDO

It can delete the PDO or object.

PDO File Information Edition

NODE ID Setting

NODE ID must be set for PDO file, it is 0 as default. This parameter is used to calculate COB-ID. For example, there is \$NodeID+0x408 in COB-ID, if **NODE ID** is set as 10(Decimal), then COB-ID=0x408+0xa=0x412

Note:NODE ID must be the same as the Node ID in the fieldbus configuration in Kinco HMIware software.

Additionally, there are other parameters like **SYS COB ID**, **Communication Cycle Period**, **Guard Time**, **Life Time Factor** as shown in following figure.

SYNC COB ID:
128
Comm Cycle Period(us)
0
Guard Time(ms):
0
Life Time Factor:
0

PDO information includes Receive PDO and Send PDO Receive PDO-Mapping Send PDO-Mapping

Their edition methods are the same.

After	finishing	edition,then	press	Save PDO	setting	file	to	save	PDC) config	uration
	C	ch can generat						Load		setting	
		file for editin		J me.wean	while,user	s can p	oress				

1. Upload/Download

C Ethernet IP: 192 .168 .100 .24	1 Port: 21845
C USB	
• Serial COM: COM1 🗸	
Progress	
Operation	
	Select file Downloa
	Upload

It can download the PDO file into HMI for CAN bus communication.And it can also upload the PDO file from HMI for edition.

Procedure for download:

(1) Communication Settings

Select connection method. There are 3 optional methods: Ethernet, USB and Serial.

(2) Select PDO file

Press button	Select	file	to select the PDO file which you want to download.
Press button			to select the PDO file which you want to download.

(3) Click button Download to download the PDO file into HMI.

Procedure for upload:

Click button Upload, then enter the name for PDO file and press Save to upload the PDO file from HMI.After finishing uploading, the PDO file can be edited.